

## *Advanced Programming Topics*

### *Algorithm analysis and design - dynamic programming*

#### *Lecture 9*

*James Marshall*

In lecture 1 we saw an efficient solution to computing the Fibonacci numbers, and an inefficient solution

But what made the inefficient solution inefficient?

*Trace:  $f_8 =$*

And the efficient solution efficient?

**N.B. this change turned an exponential-time algorithm into a polynomial-time one**

*Dynamic Programming (chapter 15 in CLRS)*

*Dynamic Programming* is a technique for efficient solution of problems having:

1. *(Optimal) substructure* —

the (optimal) solution to a problem contains the (optimal) solutions to subproblems ('*optimal*' refers to the frequent usage of dynamic programming in optimisation problems (next lecture))

2. *Overlapping independent subproblems* —

subproblems form part of the solution to multiple other problems (*cf.* 'regular' divide-and-conquer problems in which each divide step generates new and non-overlapping subproblems)

## *Subproblem Graphs*

Like *recursion trees*, but *subproblem graphs* show the relationships between all the *distinct* subproblems (vertices), with a directed edge from problem  $x$  to problem  $y$  showing that a solution to problem  $x$  requires a solution to problem  $y$

*Example: Subproblem Graph for Fibonacci Numbers*

## *Identifying and Implementing Dynamic Programming Algorithms in Haskell*

To identify that a dynamic programming algorithm may solve a problem, and then implement one:

1. Determine whether the description of the solution to a problem shows that the problem exhibits (optimal) substructure (see above) — *e.g.*

*“if we work out that the quickest train route from London to Sheffield includes a stop in Derby, we have also worked out the quickest train route from London to Derby”*

2. Determine whether the subproblems can be solved *independently* (does solving one subproblem affect how we solve a different subproblem? Often it doesn't, but sometimes it does...) — *e.g.*

*“working out the optimal route from London to Birmingham doesn't change how we work out the optimal route from London to Nottingham”*

3. Determine whether solutions to subproblems are used in multiple different solutions (if not then simple recursion will suffice) — *e.g.*

*“in working out the quickest train route from London to Sheffield we evaluate multiple routes that all require us to know the quickest route from London to Derby”*

4. Implement using *top-down recursion with memoization*

- A. start by asking for the answer to the original question (e.g. the 100th Fibonacci number), defined recursively in terms of the answers to smaller questions - hence *top-down*
- B. when a value is computed, it is *memoized* (stored) in an efficient data structure
- C. when a value is required, it is searched for in the structure first; if not found then it is computed recursively

**Many languages let you define functions as being automatically memoized. Alternatively, use a data structure to store computed values, e.g. `Data.Map` in Haskell. For simple enough recursions (e.g. the Fibonacci example of lecture 1) it may be possible to keep track of a small number of memoized values at each step in the recursion**